

BA (HONS) COMPUTER VISUALISATION AND ANIMATION

Answer FOUR questions	Year: 1
	Time: 9.30-12.30
	Date: 5/6/2006
MATHEMATICS FOR COMPUTER GRAPHICS 1	
Calculators may be used.	
Graph paper will be provided.	

Continued 24/11/06

- 1.1 Compute the value of X_b for the following where the subscript represents the base of the number.
 - a: $X_3 = 24_{10}$
 - b: $X_4 = 2_{10} \sqrt{100_5}$
 - c: $X_8 = \sqrt{1001_2 \times 100_2}$
 - d: $X_5 = 121_5 + 101_4$
 - e: $X_2 = (100_8)^{\frac{1}{2}}$

[5 marks]

- 1.2 Express the sum of the first five prime numbers as a binary number.

 [5 marks]
- 1.3 Define the meaning of the following and give an example of each.
 - a: a rational number
 - b: a scalar quantity
 - c: a quaternion
 - d: a complex number
 - e: a vector quantity

[5 marks]

- 1.4 Illustrate how $\sqrt{-1}$ rotates a complex number through 90°. **[5 marks]**
- 1.5 Simplify the following complex numbers.
 - a: (1+i2)+(2-i3)
 - b: (-1-i2)-(-4-i3)
 - c: $(2+i4)\times(3+i5)$
 - d: $(1+i)^2$
 - **e**: $i^1 + i^2 + i^3 + i^4$

[5 marks]

2.1 Prove the following identities.

a:
$$\tan \alpha = \frac{\sin \alpha}{\cos \alpha}$$

b:
$$\sin^2 \alpha + \cos^2 \alpha = 1$$

c:
$$1 + \tan^2 \alpha = \sec^2 \alpha$$

[6 marks]

Sketch and annotate the graphs of the following functions over the range $0 \le \alpha \le 2\pi$ radians.

a: $2\sin\alpha$

b: $\sin 3\alpha$

c:
$$\sin^2 \alpha$$

[6 marks]

2.3 Simplify the following expressions.

a:
$$\log(10^{2\sin 90^{\circ}})$$

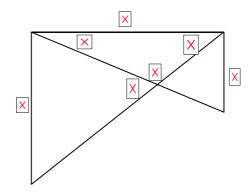
b:
$$(x-1)^3$$

C:
$$(x+y)^2 - (x-y)^2$$

[6 marks]

2.4 From the diagram (not to scale) calculate the angles $\alpha, \theta, \beta, \phi$.

[7 marks]



3.1 Given the vectors **a**, **b** and **c** compute the following vector equations.

$$\mathbf{a} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \quad \mathbf{c} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

a:
$$a+b+c$$

b:
$$\mathbf{b} - 2\mathbf{a}$$

c:
$$c-b-a$$

d:
$$\mathbf{b} \cdot \mathbf{c}$$

[4 marks]

3.2 If $\mathbf{a} = 4\mathbf{j} + 3\mathbf{k}$ and $\mathbf{b} = 2\mathbf{i} - 3\mathbf{j} + 5\mathbf{k}$ calculate the following.

c:
$$\|\mathbf{a}\|\mathbf{b}$$

[6 marks]

3.3 Given $\mathbf{r} = a_r \mathbf{i} + b_r \mathbf{j} + c_r \mathbf{k}$ and $\mathbf{s} = a_s \mathbf{i} + b_s \mathbf{j} + c_s \mathbf{k}$ and $\mathbf{r} \cdot \mathbf{s} = ||\mathbf{r}|| ||\mathbf{s}|| \cos \alpha$, where α is the angle between \mathbf{r} and \mathbf{s} , show that $\mathbf{r} \cdot \mathbf{s} = a_r a_s + b_r b_s + c_r c_s$.

[5 marks]

Using the scalar product calculate the angle between \mathbf{r} and \mathbf{s} where $\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + 6\mathbf{k}$ and $\mathbf{s} = \mathbf{i} + 4\mathbf{j} - 2\mathbf{k}$. [5 marks]

3.5 Describe how the scalar product is useful in identifying back-facing polygons.

[5 marks]

4.1 Give the algebraic equivalent of the following matrices.

a:
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

b:
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\mathbf{C} : \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 3 \\ 0 & -1 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

d:
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 4 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

[6 marks]

- 4.2 Describe the following 2D matrices and give an example of each.
 - a: a scaling matrix
 - b: a rotation matrix
 - c: a reflection matrix
 - d: a translation matrix.

[8 marks]

4.3 Describe how homogeneous coordinates provide a mechanism for combining scaling and translation matrices. Illustrate your answer with an example.

[5 marks]

4.4 Construct a 2D matrix that reflects points about the line x = 1.[6 marks]

[4 marks]

5 5.1 Describe how projective geometry can be used to create a perspective view of a 3D object, and derive the equations for computing the coordinates of points on a projection plane. [10 marks] 5.2 Given that an observer is located at the origin and is looking along the z axis, find the projection coordinates of the following 3D points (10,10,30), (20,20,40). The projection plane is 10 units from the observer and is orthogonal to the z axis. [4 marks] 5.3 Describe how a pseudo fish-eye effect can be obtained and derive the associated projective equations. [7 marks] 5.4 Describe the role of the viewing frustum in the projection process.

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6.1 Describe the geometric meaning of a, b and c in the Cartesian form of the line equation ax + by = c and illustrate your answer with an example.

[6 marks]

- Show how line equations can be used to determine whether a point is inside or outside a convex 2D polygon. In your answer describe how it is also possible to detect whether a point is located on an edge or vertex.[10 marks]
- 6.3 Compute the shortest distance from the origin to a plane if its equation is 2x+3y-4z=10. **[4 marks]**
- Describe how plane equations can be used to determine whether points are inside, outside, or located at an edge or vertex of a convex volume

 [5 marks]

25/01/2006

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